

Yu-Hsuan Yeh

✉ alice12595@gmail.com

🐙 Github

🔍 Google Scholar

🌐 Personal Website

U.S. Permanent Resident (EB-1) — No sponsorship required.

EDUCATION

Carnegie Mellon University (CMU)

Pittsburgh, PA, US

- A paper published in **IEEE TPAMI 2022**.

Master of Science in Computer Vision

Aug. 2022 - Dec. 2023

National Yang Ming Chiao Tung University (NYCU)

Hsinchu, Taiwan

- Thesis-based research program - one first author paper per year: **CVPR 2020** and **CVPR 2021 (Oral)**.

Master of Science, Artificial Intelligence Graduate Program

Sep. 2019 - Aug. 2021

National Chung Hsing University (NCHU)

Taichung, Taiwan

Bachelor of Science, Electrical Engineering

Sep. 2013 - Jun. 2017

WORK EXPERIENCE

Adobe (On-Site)

San Jose, CA, US

Applied Scientist, Firefly

Apr. 2024 - Present

- Improve the Distribution Matching Distillation efficient model for image inpainting task (Photoshop feature)
- Building up the first Firefly eval hub system
- Proposed an enhanced VQA-score metric with more image attribute-level analysis
- Designed and implemented a novel VQA-score alignment pipeline

Adobe (On-Site)

San Jose, CA, US

Machine Learning Engineer Intern

May. 2023 - Aug. 2023

- Parameter Efficiency Fine-Tuning Research

Lumachain (Remote)

Sydney, Australia

Computer Vision Intern

Feb. 2022 - Jun. 2022

- Multi-Object Tracking Project:
Building a deep-learning tracking model to monitor workers' behavior

National Tsing Hua University (On-Site)

Hsinchu, Taiwan

Research Assistant

Oct. 2018 - Oct. 2021

- Researched 360° image perception and reconstruction, with an emphasis on depth and layout estimation for indoor panoramic scenes.
- Explored 2D-to-3D transformation methods to reconstruct spatial structures from monocular 360° inputs.

Wistron NeWeb Corporation (On-Site)

Hsinchu, Taiwan

Advance Technology Development AI Lab - AI Summer Intern

Jul. 2018 - Aug. 2018

- Derain - Rain Removal Project:
Building variational autoencoder and modifying style transfer models to remove rain

RESEARCH EXPERIENCE

Illumination and Imaging Laboratory (ILIM), Carnegie Mellon University

Pittsburgh, PA, US

Graduate Research, Advised by Prof. Srinivasa Narasimhan

Jan. 2024 - Apr. 2024

- **GenAI research: Object Insertion on Road Scene**
Using a diffusion inpainting model for scene editing

Enriched Vision Applications Lab, National Yang Ming Chiao Tung University

Hsinchu, Taiwan

Graduate Research, Advised by Prof. Wei-Chen Chiu,

Sep. 2019 - Aug. 2021

Prof. Min Sun and NEC Lab Researcher Yi-Hsuan Tsai

- **360 Degree Indoor Room Layout Estimation**
Utilizing depth information to improve room layout prediction

Vision Science Lab, National Tsing Hua University

Hsinchu, Taiwan

Graduate Research, Advised by Prof. Min Sun,

Oct. 2018 - Sep. 2019

Prof. Wei-Chen Chiu and NEC Lab Researcher Yi-Hsuan Tsai

- **360 Degree Depth Estimation**
Fusing depth information from two different projections

Mediacore Lab, National Cheng Kung University

Tainan, Taiwan

Graduate Research, Supervised by Prof. Jar-Ferr Yang

Jul. 2017 - Oct. 2018

- **Unsupervised Monocular Depth Estimation Refinement**
Utilizing instance segmentation algorithm to capture objects for accurate depth estimation

PUBLICATIONS

- **BiFuse++: Self-supervised and Efficient Bi-projection Fusion for 360 Depth Estimation** [[paper](#)][[github](#)]
Fu-En Wang, Yu-Hsuan Yeh, Yi-Hsuan Tsai, Wei-Chen Chiu, Min Sun
[TPAMI 2022]
 - We propose a new fusion module and Contrast-Aware Photometric Loss to improve the performance of BiFuse and increase the stability of self-training on real-world videos.
- **LED²-Net: Monocular 360° Layout Estimation via Differentiable Depth Rendering** [[paper](#)][[github](#)]
Yu-Hsuan Yeh, Fu-En Wang*, Min Sun, Wei-Chen Chiu, Yi-Hsuan Tsai*
[CVPR 2021 Oral]
 - We propose a differentiable layout-to-depth procedure to convert the 360° layout representation into the 360° horizon-depth map, thus enabling the training objective for our layout estimation network to take advantage of 3D geometric information.
- **BiFuse: Monocular 360° Depth Estimation via Bi-projection Fusion** [[paper](#)][[github](#)]
Yu-Hsuan Yeh, Fu-En Wang*, Min Sun, Wei-Chen Chiu, Yi-Hsuan Tsai*
[CVPR 2020]
 - We propose a two-branch neural network leveraging two common projections – equirectangular and cubemap projections – as inputs to predict the depth map of a monocular 360° image.

DATASET PAPER

- **LayoutMP3D: Layout Annotation of Matterport3D** [[paper](#)][[github](#)]
Yu-Hsuan Yeh, Fu-En Wang*, Min Sun, Wei-Chen Chiu, Yi-Hsuan Tsai*
[Technical Report]
 - We release the first real-world dataset containing paired depth and layout annotations.

HONORS & AWARDS

- **Outstanding graduate student award:** around 8 people granted every year (< 5%) Jun. 2021
 - in College of Electrical and Computer Engineering
- **Outstanding thesis awards:** only 3 master thesis awards were given Aug. 2021
 - Institute for Public Policy Research(IPPR)
 - Conference on Computer Vision, Graphics, and Image Processing(CVGIP)
- **NovaTek Scholarship:** around 14 people granted every year (< 5%) Aug. 2021
- **NovaTek Scholarship:** around 14 people granted every year (< 5%) Aug. 2020
- **MOST AI scholarship:** a travel subsidy for CVPR 2020 Jun. 2020

INVITED TALKS

- Jul. 2020: CVPR2020 paper sharing [BiFuse], MediaTek Inc and National Taiwan University
- Jul. 2020: CVPR2020 paper sharing [BiFuse], AILabs